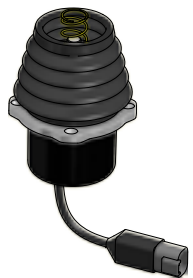


JOYSTICK FAMILY & TYPE	MAIN BASE CONFIGURATION	YY / XX AXES CONTROL CONFIG.	TYPE OF GRIP	GRIP CONFIGURATION	CONNECTOR TYPE
JHM Heavy duty / Multi-axis hall effect type joystick controller	L2S Single axis, bidirectional	ANL Analog signal 0.5>2.5>4.5 VDC power supply range = 5 VDC ±5%	IL Cylindrical knob	Refer to the grip ordering information for z z e k k axes (push-buttons & proportional controls on grips)	3 Flying leads 25 cm length
	L4C Dual axes, cross movement	ANH Analog signal 0.5>2.5>4.5 VDC power supply range = 8-32 VDC	IC Cylindrical		4 Male connector, 12 poles, Deutsch DT04-12P, 25 cm cable length
	L4D Dual axes, all diagonals	AVS Center tap output signal with digital directional signals	IE Multi-function ergonomic		5 Male connector, 4 poles, Deutsch DT04-4P, 25 cm cable length (for CANbus version only)
		MLT adjustable output signal for closed loop prop. actuators	MS Multi-function ergonomic symmetric		6 Male connector, 6 poles, Deutsch DT04-6P, 25 cm cable length
		RTM adjustable output signal for closed loop prop. actuators	MG Multi-function ergonomic right hand		7 Male connector, 8 poles, Deutsch DT04-8P, 25 cm cable length
		PWM Pulse with modulation current output factory preset or set via PC	HL Multi-function ergonomic left hand		
		TCN 1 PWM output in combination with up to 4 on-off channels	HR Multi-function ergonomic right hand		
		CAN CANbus version for connection to CANbus line J1939 protocol			

Note:
for TCN, PWM and MLT versions, a 4 poles, Deutsch DT04-4P connector is always included

EXAMPLE:



JHM-L4D/ANH-6
BASE

+



MS/0000/2FPR/R000
GRIP

=

JHM-L4D/ANH-MS/0000/2FPR/R000-6
COMPLETE JOYSTICK
(with 6 poles Deutsch connector)