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JHM - [ ] / [ ] - [ ] / [ ] - [ ]

Joystick family & type

JHM Heavy duty / Multi-axis hall effect type joystick controller

Main base configuration

L2S Single axis, bidirectional

L4C Dual axes, cross movement

L4D Dual axes, all diagonals

YY / XX axes control config.

ANL Analog signal 0.5>2.5>4.5 VDC power supply range = 5 VDC ±5%

ANH Analog signal 0.5>2.5>4.5 VDC power supply range = 8-32 VDC

AVS Center tap output signal with digital directional signals

MLT adjustable output signal for closed loop prop. actuators

RTM adjustable output signal for closed loop prop. actuators

PWM Pulse with modulation current output factory preset or set via PC

TCN 1 PWM ouput in combination with up to 4 on-off channels

CAN CANbus version for connection to CANbus line J1939 protocol

Type of grip

IL Cylindrical knob

IC Cylindrical

IE Multi-function ergonomic

MS Multi-function ergonomic symmetric

MG Multi-function ergonomic right hand

HL Multi-function ergonomic left hand

HR Multi-function ergonomic right hand

Grip Configuration

Refer to the grip ordering information for **zz** e **kk** axes (push-buttons & proportional controls on grips)

Connector type

3 Flying leads 25 cm length

4 Male connector, 12 poles, Deutsch DT04-12P, 25 cm cable length

5 Male connector, 4 poles, Deutsch DT04-4P, 25 cm cable length (for CANbus version only)

6 Male connector, 6 poles, Deutsch DT04-6P, 25 cm cable length

7 Male connector, 8 poles, Deutsch DT04-8P, 25 cm cable length

Note:
for TCN, PWM and MLT versions, a 4 poles, Deutsch DT04-4P connector is always included

EXAMPLE:

JHM-L4D/ANH-6
BASE

+

MS/0000/2FPR/R000
GRIP

=

JHM-L4D/ANH-MS/0000/2FPR/R000-6
COMPLETE JOYSTICK
(with 6 poles Deutsch connector)

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